

Math 4200

Wednesday September 9

1.5: From last weeks notes: Review of chain rule for curves and CR equations; precise discussion of the differential map in our context, which is also used more generally for differentiable transformations between Euclidean spaces and differentiable manifolds; new in today's notes: proofs of the full CR theorem and inverse function theorem using Math 3220 ideas.

Announcements:

Warmup exercise: Recall the CR equations for the partial derivatives of the real and imaginary parts of a complex differentiable function $f(z)$:

$$f(x + i y) = u(x, y) + i v(x, y)$$
$$CR \quad \begin{cases} u_x = v_y \\ v_x = -u_y \end{cases}$$

Re-derive the CR equations using the chain rule for curves and the identity

$$f'(z) = f_x = \frac{1}{i} f_y$$

Friday review

2) Theorem (Chain rule for curves) If f is differentiable at z_0 and $\gamma: I \subseteq \mathbb{R} \rightarrow \mathbb{C}$ is a parametric curve $\gamma(t) = x(t) + iy(t)$ such that $\gamma(t_0) = z_0$ and such that $\gamma'(t_0) = x'(t_0) + iy'(t_0)$ exists, then

$$(f \circ \gamma)'(t_0) = \underbrace{f'(\gamma(t_0))}_{\text{scaled by mod.}} \underbrace{\gamma'(t_0)}_{\text{rotated by } \arg f'(z_0)}$$

proof We can use the affine approximation formula for f , at $\gamma(t_0)$, and mimic the proof of Theorem 1.

approx for f :

$$f(\gamma(t)) = f(\gamma(t_0)) + f'(\gamma(t_0))(\gamma(t) - \gamma(t_0)) + h \varepsilon(h) \quad f \text{ diffble @ } z_0$$

$$\frac{f(\gamma(t)) - f(\gamma(t_0))}{t - t_0} = f'(\gamma(t_0)) \frac{\gamma(t) - \gamma(t_0)}{t - t_0} + \left(\frac{h \varepsilon(h)}{t - t_0} \right) \rightarrow \gamma'(t_0) \cdot 0 = 0$$

$\lim_{t \rightarrow t_0} : (f \circ \gamma)'(t_0) = f'(\gamma(t_0)) \gamma'(t_0) + 0$

Domain-range geometry implied by the chain rule for curves. Consider the curve $\gamma(t)$ which has image in the domain of f , along with the curve $f \circ \gamma(t)$ which has image in the range of f . Let $f'(\gamma(t_0)) = r e^{i\theta}$. Then the image curve tangent vector is obtained by rotating the original curve tangent vector by r and scaling it by θ .

$$(f \circ \gamma)'(t) = \underbrace{f'(\gamma(t))}_{\text{scaled by mod.}} \gamma'(t)$$

@ t_0 $|f'(z_0)| e^{i \arg f'(z_0)} \gamma'(t_0)$
 scaled by mod. rotated by $\arg f'(z_0)$

Friday notes

Conformal transformations and differential map discussion:

(i) The precise definition of the *tangent space* at $z_0 \in \mathbb{C}$ is the set of all *tangent vectors* there, i.e. tangent vectors to curves passing through z_0 :

$$T_{z_0} \mathbb{C} := \left\{ \gamma'(t_0) \mid \gamma \text{ is differentiable at } t_0 \text{ and } \gamma(t_0) = z_0 \right\}$$

(ii) If $f(z)$ is a function from \mathbb{C} to \mathbb{C} that arises from a real-differentiable function $F: A \subseteq \mathbb{R}^2 \rightarrow \mathbb{R}^2$, then the *differential of f at z_0* is defined by

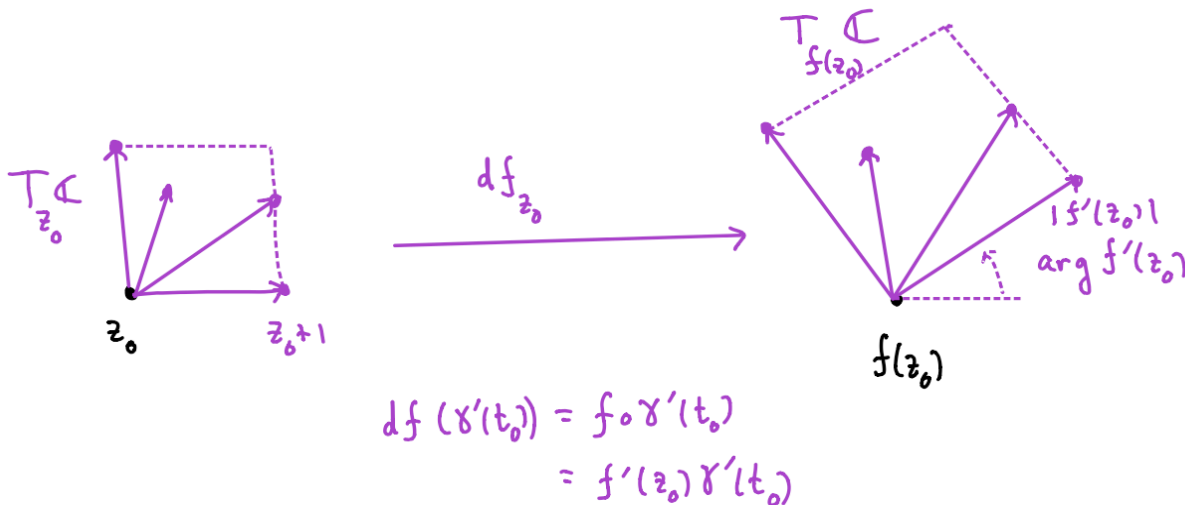
$$df_{z_0}(\gamma'(t_0)) := (f \circ \gamma)'(t_0).$$

$$df_{z_0}: T_{z_0} \mathbb{C} \rightarrow T_{f(z_0)} \mathbb{C}.$$

(iii) By the chain rule for curves, if $f(z)$ is complex differentiable at z_0 , then

$$df_{z_0}(\gamma'(t_0)) := (f \circ \gamma)'(t_0) = f'(z_0)\gamma'(t_0)$$

Geometrically, this means that for complex differentiable functions f , the differential map is a linear transformation from $T_{z_0} \mathbb{C}$ to $T_{f(z_0)} \mathbb{C}$ which is a rotation-dilation.



(iv) A function $f: \mathbb{C} \rightarrow \mathbb{C}$ is called *conformal* at z_0 iff its differential transformation preserves angles between tangent vectors. Since rotation-dilations have this property, a function f which is complex differentiable at z_0 , and for which $f'(z_0) \neq 0$, is conformal at z_0 . (It turns out that if f is conformal at z_0 and also preserves orientations of pairs of tangent vectors, then f is complex differentiable at z_0 .)

Illustration. Consider

$$f(z) = z^2, z_0 = 1 + i,$$

$$f(z_0) = 2i, f'(z_0) = 2 + 2i = 2\sqrt{2} e^{i\frac{\pi}{4}}$$

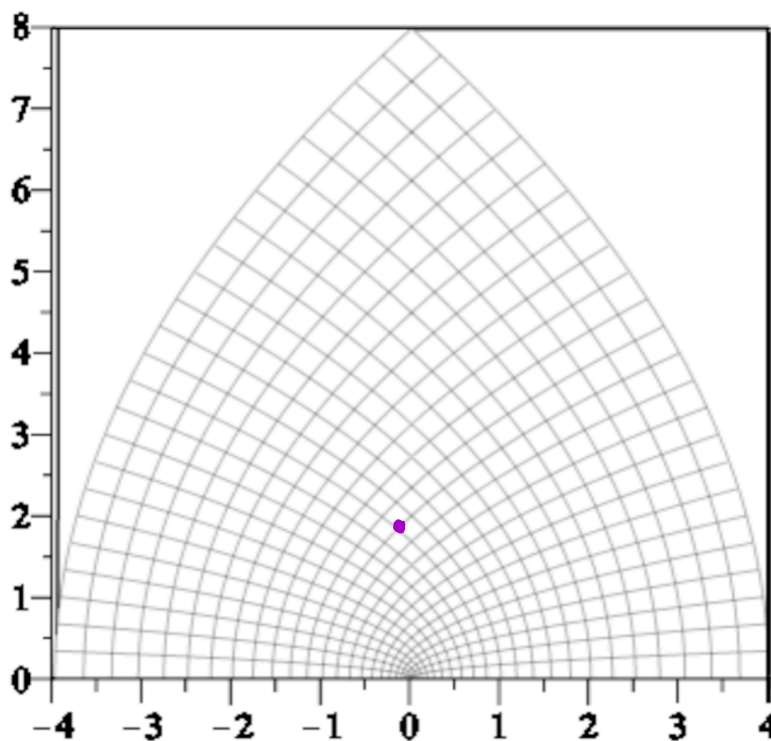
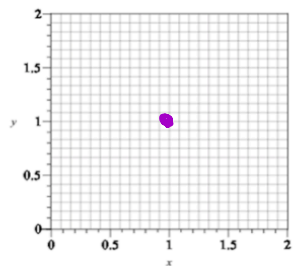
Below, are parts of a rectangular coordinate grid in the domain, and the image of that grid in the range space.

- a) Why are the images of the real and imaginary grid lines also perpendicular?
- b) Find the formula for the differential map

$$df_{z_0} : T_{z_0} \mathbb{C} \rightarrow T_{f(z_0)} \mathbb{C}$$

and illustrate the rotation dilation.

*finish discussion
on Wed. next week.*



The next two theorems are applications of Math 3220 analysis and the correspondence between $f: A \subseteq \mathbb{C} \rightarrow \mathbb{C}$, and $F: A \subseteq \mathbb{R}^2 \rightarrow \mathbb{R}^2$: For each

$$f(x + i y) = u(x, y) + i v(x, y)$$
$$f: A \subseteq \mathbb{C} \rightarrow \mathbb{C}, A \text{ open}$$

there corresponds

$$F(x, y) = (u(x, y), v(x, y))$$
$$F: A \subseteq \mathbb{R}^2 \rightarrow \mathbb{R}^2, A \text{ open}$$

Theorem (full CR Theorem) Let $A \subseteq \mathbb{C}$ open, $f: A \rightarrow \mathbb{C}$, $z_0 \in A$. Write

$$f(z) = f(x + i y) = u(x, y) + i v(x, y)$$

where

$$u(x, y) = \operatorname{Re}(f(x + i y)), v(x, y) = \operatorname{Im}(f(x + i y))$$

Then if f is complex differentiable at $z_0 = x_0 + i y_0$ if and only if the following two conditions hold:

(1) The *Cauchy-Riemann equations* hold at (x_0, y_0) :

$$u_x(x_0, y_0) = v_y(x_0, y_0)$$
$$u_y(x_0, y_0) = -v_x(x_0, y_0);$$

AND

(2) $F(x, y) = (u(x, y), v(x, y))$ is *Real differentiable* at (x_0, y_0) in the affine approximation sense you discussed in Math 3220. In particular real differentiability is implied by the condition that all of the partial derivatives u_x, u_y, v_x, v_y exist and are continuous in a neighborhood of (x_0, y_0) .

proof:

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$$f(z) = u(x, y) + iv(x, y)$$

$$f'(z_0) = a + bi \text{ exists}$$

$$\Leftrightarrow f(z_0 + h) = f(z_0) + (a + bi)h + h\varepsilon(h)$$

$$\text{s.t. } \lim_{h \rightarrow 0} \varepsilon(h) = 0$$

write
 $z = z_0 + h$,

$$\Leftrightarrow \lim_{z \rightarrow z_0} \frac{|f(z) - f(z_0) - (a + bi)(z - z_0)|}{|z - z_0|} = 0$$

$$\Leftrightarrow \lim_{(x, y) \rightarrow (x_0 + iy_0)} \frac{|u(x, y) + iv(x, y) - u(x_0) - iv(x_0, y_0) - (a + bi)(x - x_0 + i(y - y_0))|}{|(x - x_0) + i(y - y_0)|} = 0$$

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$$F(x, y) = (u(x, y), v(x, y))$$

$$\Leftrightarrow \lim_{(x, y) \rightarrow (x_0, y_0)} \frac{\left\| \begin{bmatrix} u(x, y) \\ v(x, y) \end{bmatrix} - \begin{bmatrix} u(x_0, y_0) \\ v(x_0, y_0) \end{bmatrix} - \begin{bmatrix} a & -b \\ b & a \end{bmatrix} \begin{bmatrix} x - x_0 \\ y - y_0 \end{bmatrix} \right\|}{\left\| \begin{bmatrix} x \\ y \end{bmatrix} - \begin{bmatrix} x_0 \\ y_0 \end{bmatrix} \right\|} = 0$$

$\Leftrightarrow F$ is real-diff'ble @ (x_0, y_0)

with differential matrix @ (x_0, y_0) :

$$\begin{bmatrix} u_x & u_y \\ v_x & v_y \end{bmatrix} = \begin{bmatrix} a & -b \\ b & a \end{bmatrix}$$

■

Theorem (Inverse function theorem) Let f be complex differentiable in a neighborhood of z_0 , with $f'(z_0) \neq 0$ and $f'(z)$ continuous. Then there exist open sets U, V with $z_0 \in U, f(z_0) \in V$ such that $f: U \rightarrow V$ is a bijection and $f^{-1}: V \rightarrow U$ is also analytic. Furthermore

$$(f^{-1})'(f(z)) = \frac{1}{f'(z)}$$

$\forall z \in U.$

proof:

$f: A \subset \mathbb{C} \rightarrow \mathbb{C}$

f analytic in a nbhd A of z_0 , $f'(z)$ continuous on A , $f'(z_0) \neq 0$,

$f(z) = f(x+iy) = u(x,y) + iv(x,y)$ ①

$f'(z_0) = a + bi = f_x(z_0) = -if_y(z_0)$

$(a = u_x(x_0, y_0) = v_y(x_0, y_0)$
 $b = v_x(x_0, y_0) = -u_y(x_0, y_0))$

$F: A \subset \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$F(x,y) = \begin{bmatrix} u(x,y) \\ v(x,y) \end{bmatrix}$ real differentiable in a nbhd of (x_0, y_0)

$DF(x,y) = \begin{bmatrix} u_x & u_y \\ v_x & v_y \end{bmatrix}$

$DF(x_0, y_0) = \begin{bmatrix} a & -b \\ b & a \end{bmatrix}$ is invertible ($\det = a^2 + b^2 = |f'(z_0)|^2$)

② \Downarrow 3220 inverse fun thm

$\exists U, V$ open, $(x_0, y_0) \in U \subset A$; $F(x_0, y_0) \in V$

s.t. $F: U \rightarrow V$ is a bijection, and $F^{-1}: V \rightarrow U$ is real differentiable.

Furthermore, by the 3220 chain rule and since $F^{-1}(F(x,y)) = (x,y) \quad \forall (x,y) \in U$

the matrix product of derivative matrices $DF^{-1}(F(x,y)) DF(x,y) = I \leftarrow$ identity matrix

In particular,

$DF^{-1}(F(x,y)) = [DF(x,y)]^{-1}$
 $\forall (x,y) \in U.$

Note, $DF(x,y) = \begin{bmatrix} \alpha & -\beta \\ \beta & \alpha \end{bmatrix}$, so

$DF^{-1}(F(x,y)) = \frac{1}{\alpha^2 + \beta^2} \begin{bmatrix} \alpha & \beta \\ -\beta & \alpha \end{bmatrix}$
is also a rotation-dilation

③ \Leftarrow

$\exists U, V$ open, $z_0 \in A \subset U, f(z_0) \in V$

s.t. $f: U \rightarrow V$ is a bijection, and $f^{-1}: V \rightarrow U$

has real differentiable counterpart F^{-1} whose partials satisfy CR eqns

$\Rightarrow f^{-1}$ is analytic on V .

And since $f^{-1}(f(z)) = z$

$(f^{-1})'(f(z)) \cdot f'(z) = 1$

$(f^{-1})'(f(z)) = \frac{1}{f'(z)}, \quad \forall z \in U.$

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Loose end: (applies to the hw problem 1.5.16)

Theorem Let A be an open connected set in \mathbb{C} , $f: A \rightarrow \mathbb{C}$ analytic, with $f'(z) = 0 \forall z \in A$. Then f is constant.

proof: For open sets, *connected* and *path-connected* are equivalent. Any continuous path connecting two points in A can be approximated with a continuously differentiable (C^1) path connecting the same two points. Let z_0 be any fixed point in A . Let $z \in A$ be any other point. Let γ be a C^1 curve,

$$\begin{aligned}\gamma: [a, b] &\rightarrow A \\ \gamma(a) &= z_0 \\ \gamma(b) &= z\end{aligned}$$

Then by the fundamental theorem of Calculus (applied to the real and imaginary parts of f),

$$\begin{aligned}f(z) - f(z_0) &= \int_a^b \frac{d}{dt} f(\gamma(t)) dt \\ &= \int_a^b f'(\gamma(t)) \gamma'(t) dt \\ &= \int_a^b 0 dt = 0.\end{aligned}$$

QED

(Or, you showed in Math 3220 that a continuously differentiable function of several variables defined on an open connected set and with all partial derivatives equal to zero, is constant. That theorem applies here, since the partials of $\operatorname{Re}(f)$, $\operatorname{Im}(f)$ are zero if $f' \equiv 0$.)